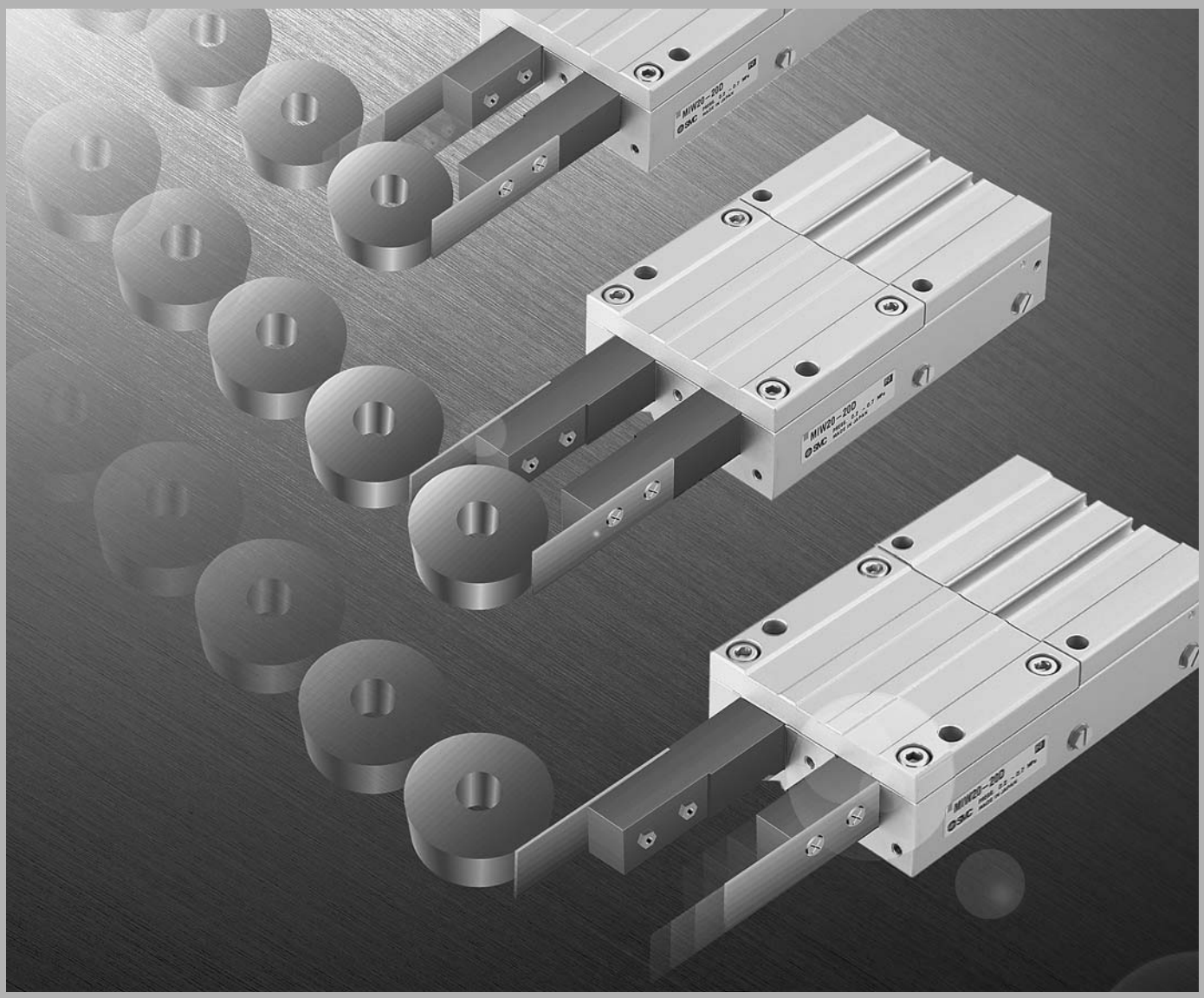
Escapements

Series MIW/MIS

ø8, ø12, ø20, ø25, ø32

Ideal for separating and feeding individual parts from vibratory feeders, magazines, and hoppers.



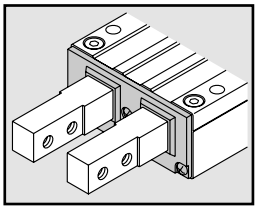
Series variations

Series	Bore size (mm)	Stroke (mm) 8	10	12	20	25	30	32	50	Finger option	Stroke adjuster	Scraper
MIW	8	●								●	●	●
	12			●						●	●	●
	20				●					●	●	●
	25					●				●	●	●
	32							●		●	●	●
MIS	8	●								●	●	●
	12		●							●	●	●
	20		●		●					●	●	●
	25						●		●	●	●	●
	32						●		●	●	●	●

Ideal for separating and from vibratory feeders,

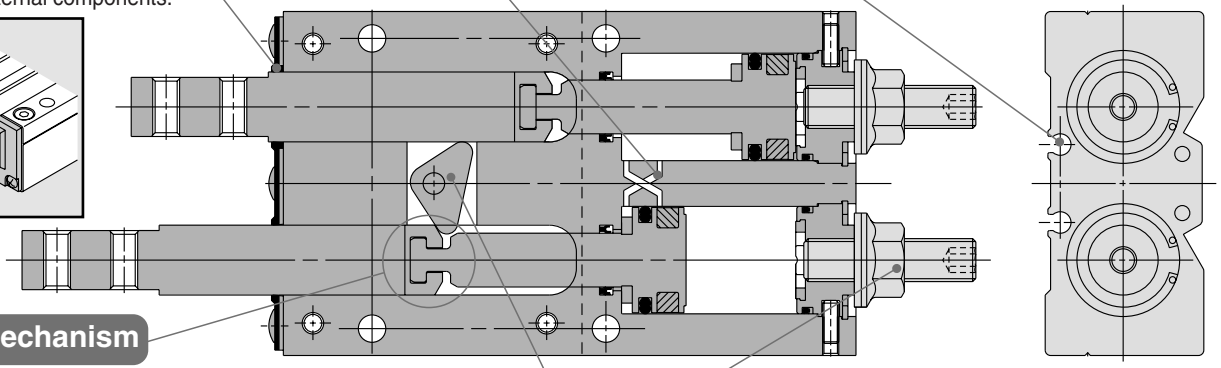
Scraper (optional)

Optional scraper prevents entry of dust to protect internal components.



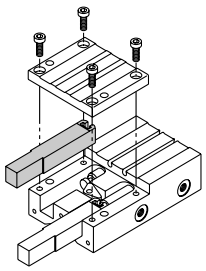
Air passage

Auto switch capable



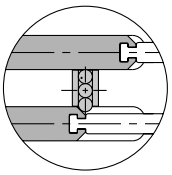
Floating mechanism

Improves life of the escapement by preventing eccentric loads causing damage to the piston and the seals.
As this mechanism separates the fingers from the piston, it is possible to replace the fingers with ease when required.



Interlocking

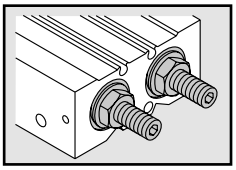
Provides reliable performance of the escapement by interlocking the two piston rods with a cam mechanism and control of air passage to the pistons.



For ø25 and ø32, lock mechanism for heavier load is available.

Stroke adjuster (optional)

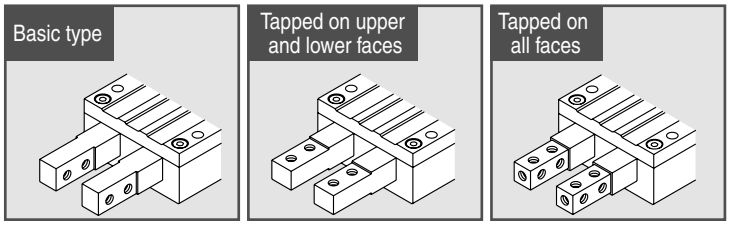
Optional stroke adjuster for precise adjustment of the retracted position of each piston rod.



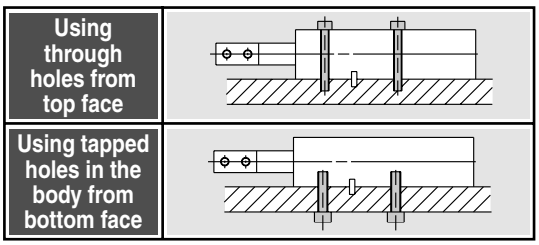
Three variations of fingers

Flexibility in mounting the finger options.

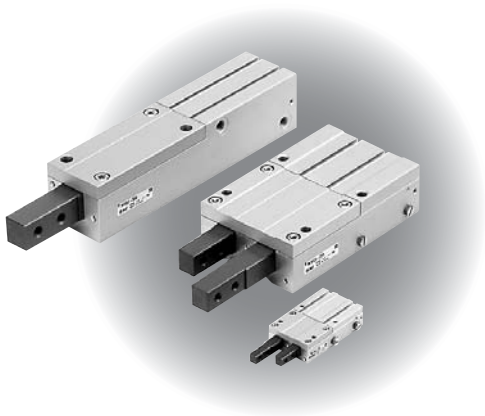
Finger options



Mounting is possible from 2 directions.

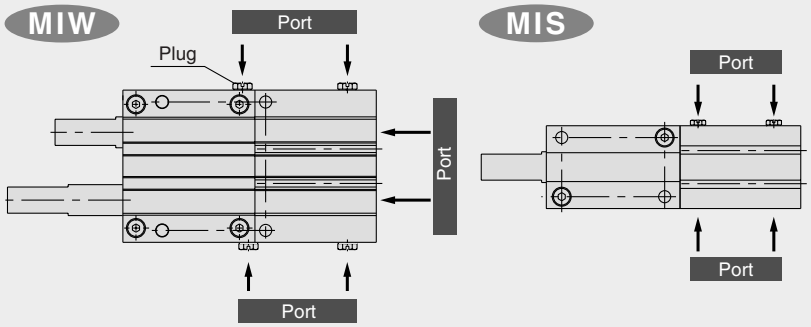


∗ Positioning pin holes allow for easy mounting.



Piping from three directions are possible (Two directions for MIS)

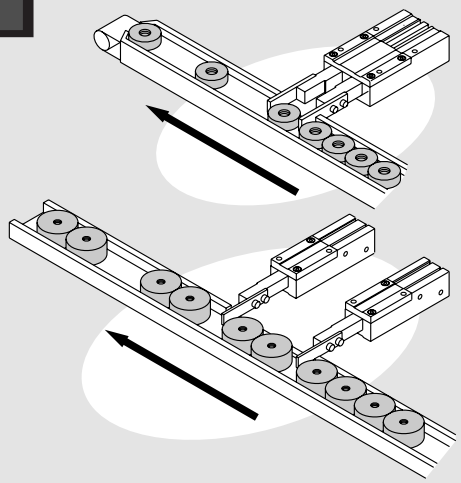
Port position can be adjusted along with setting conditions by changing plug position.



SMC

feeding individual parts magazines, and hoppers.

Application examples

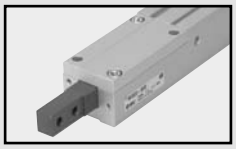


MIW **Double finger type**

Single valve operation easily separates and feed each work piece.

MIS **Single finger type**

Operating speed and mounting position can be set according to the size of work piece and its operating condition.

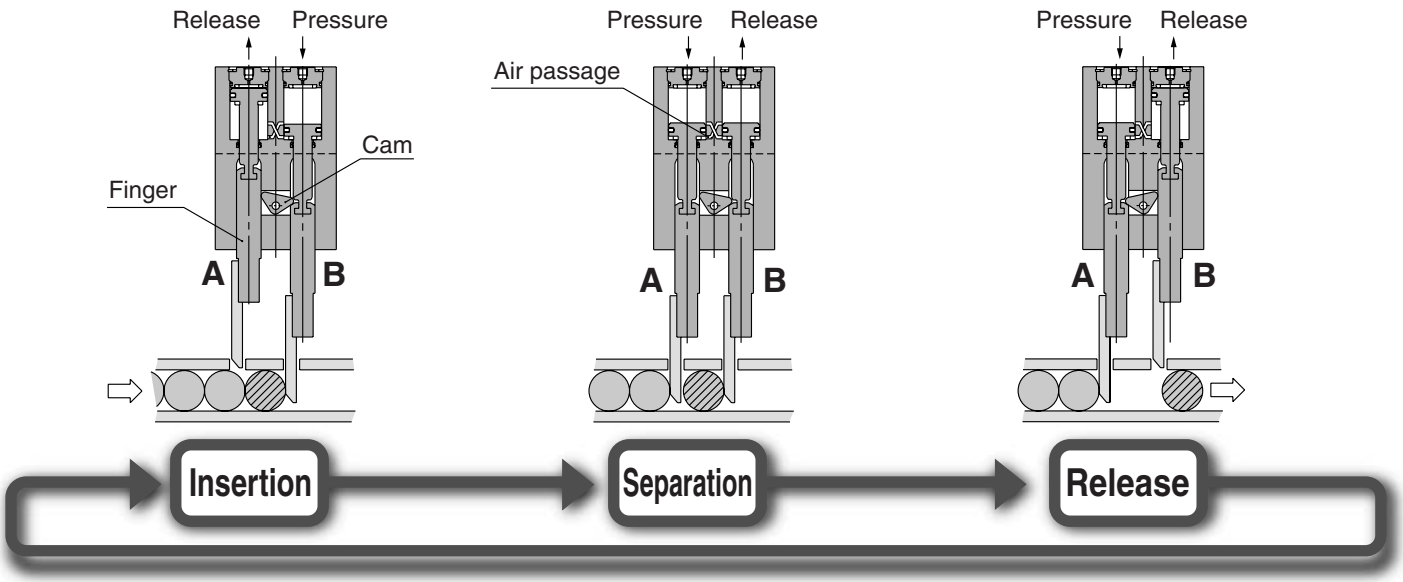


Working principle

The cam locks Finger B.

When Finger A is extended to reach the stroke end, air is supplied to retract Finger B.

Extension of Finger A rotates the cam to unlock Finger B and lock finger A to allow retraction of Finger B.



Series MIW/MIS
Model Selection 1

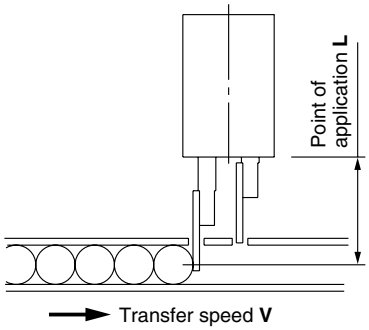
Model Selection

Selection procedure

Procedure 1 Condition confirmation → **Procedure 2** Confirmation of impact by work piece → **Procedure 3** Confirmation of allowable lateral load

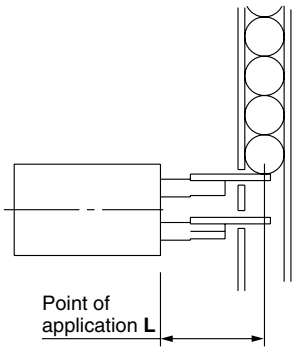
Procedure 1 Confirmation of conditions

● The work piece moves horizontally on the conveyor.



Operation conditions
- Operating pressure P (MPa)
- Work piece mass m (Kg)
- Work piece quantity x (Qty.)
- Point of application L (mm)
- Work piece transfer speed V (m/min)
- Coefficient of friction between the work piece and conveyor μ

● When the work piece drops vertically from a shooter, etc.



Operation conditions
- Operating pressure P (MPa)
- Work piece mass m (Kg)
- Work piece quantity x (Qty.)
- Point of application L (mm)
- Distance of work piece drop H (mm)
- Gravitational acceleration g (m/s²)

Procedure 2 Confirmation of impact

From the graph of operating range, obtain the point of intersection of the total mass of the work piece $x \cdot m$ (kg) indicated by the axis of ordinates and the transfer speed V (m/min) indicated by the axis of abscissas. Select a model so that the intersection will fall below the point of application L indicated by a line.

1. Calculation of work piece collision speed
   The collision speed V is calculated from the distance of work piece fall H.

   Work piece collision speed $V = \sqrt{2gH/1000} \times 60$ (m/min)

2. From the graph of operating range, obtain the intersection of the total mass of the work piece $x \cdot m$ (kg) indicated by the axis of ordinates and the collision speed V (m/min) obtained by calculation. Select a model so that the intersection will fall below the point of application L indicated by a line.

Procedure 3 Confirmation of allowable lateral load

1. Calculation of applied lateral load F
   The lateral load F equals the coefficient between the work piece and the conveyor. Thus, from the total amount of the work piece and coefficient of friction,
   $F = \mu \cdot x \cdot m \cdot g$ (N)

1. Calculation of applied lateral load
   The lateral load F equals the total load of the work piece.
   Thus, $F = x \cdot m \cdot g$ (N)

2. From the graph of allowable lateral load, obtain the allowable lateral load F max from the intersection of the operating pressure and the point of application L indicated by the axis of abscissas. Select a model so that the value will be larger than the lateral load F applied in real operation.
   Lateral load: F ≤ Allowable lateral load: Fmax

Model Selection

Operating range

Procedure 1 Confirmation of conditions

● The work piece moves horizontally on the conveyor.

Operating conditions

Operating pressure	P = 0.4 MPa
Work piece mass	m = 0.1 kg
Work piece quantity	x = 10
Point of application	L = 50 mm
Work piece transfer speed	V = 12 m/min
Coefficient of friction between the work piece and conveyor	μ = 0.2

● When the work piece drops vertically from a shooter, etc.

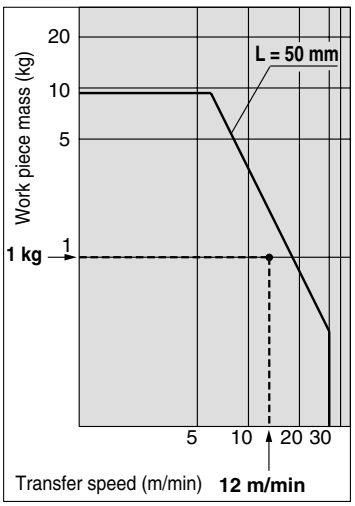
Operating conditions

Operating pressure	P = 0.4 MPa
Work piece mass	m = 0.05 kg
Work piece quantity	x = 5
Point of application	L = 60 mm
Distance of work piece drop	H = 15 mm
Gravitation acceleration	g = 9.8 m/s^2

Procedure 2 Confirmation of impact

- Obtain the total amount of the work piece.
  Total mass m = 10 x 0.1 (kg) = 1 (kg)
- Obtain the intersection of the transfer speed V and the total weight of work piece m. Confirm that the value is within the operating range of the point of application L = 50 mm

ø12



- Obtain the total amount of the work piece.
  Total mass m = 5 x 0.05 (kg) = 0.25 (kg)
- Obtain the collision speed of the work piece V.

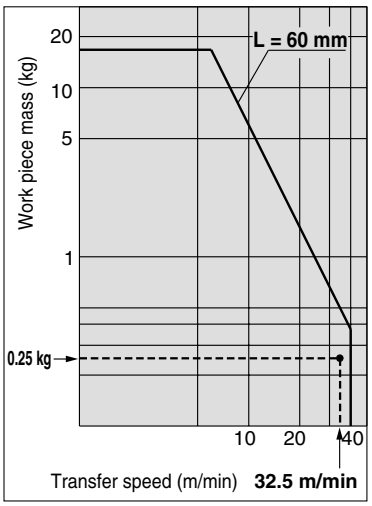
$V = \sqrt{2gH/1000} \times 60$

$= \sqrt{2 \times 9.8 \times 15/1000} \times 60$

= 32.5 (m/min)

- Obtain the intersection of the collision speed V and the total mass of the work piece m. Confirm that the value is within the operating range of the point of application L = 60 mm.

ø20

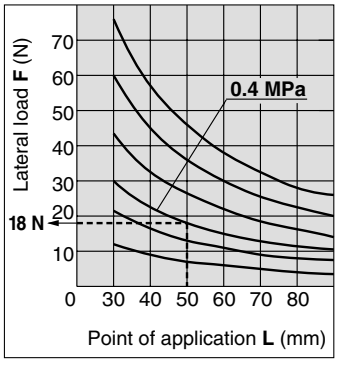


Procedure 3 Confirmation of allowable lateral load

1. Calculation of applied lateral load F
   $F = \mu \cdot N \cdot m \cdot g$ (N)
   = 0.2 x 10 x 0.1 x 9.8
   = 2.1 (N)

2. Confirmation of allowable lateral load
   From the graph, the allowable lateral load at L = 50 mm and P = 0.4 MPa is 18 N. Because 2.1 N < 18 N, it is applicable.

MIW12
MIS12



Therefore select MIW (MIS) 12.

1. Calculation of applied lateral load
   The lateral load F equals the total load of the work piece. Thus,
   F= 5 x 0.05 x 9.8
   = 2.5 (N)

2. Confirmation of allowable lateral load
   In the same way, the lateral load at L = 50 mm and P = 0.4 MPa is 48 N from the graph. Because 2.5 N < 48 N, it is applicable.

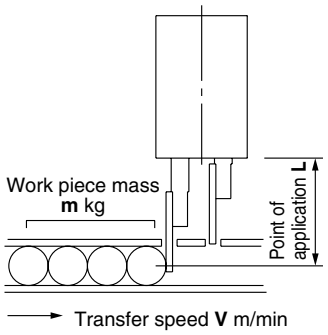
Therefore select MIW (MIS) 20.

Model Selection 2

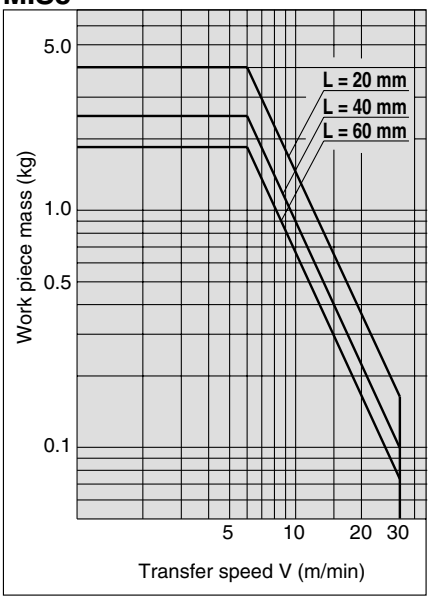
Model Selection

Operating range

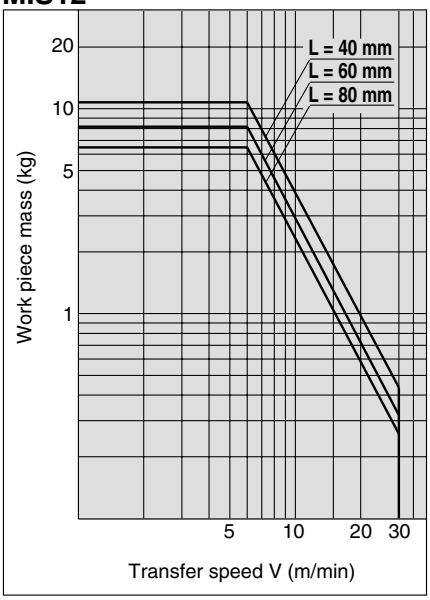
The graph at right shows conditions of the work piece to be stopped; that is, the mass, transfer speed and the operating range of the point of application L.



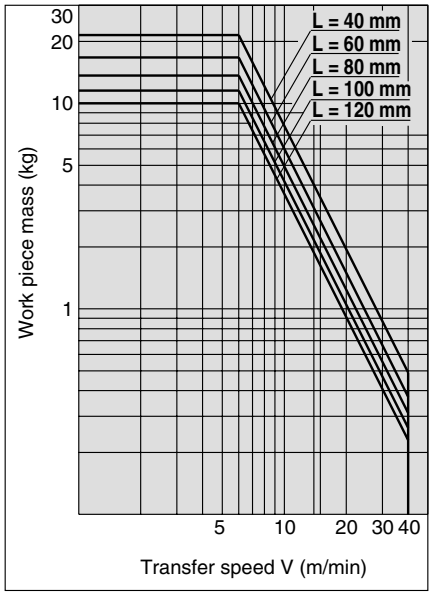
MIW8
MIS8



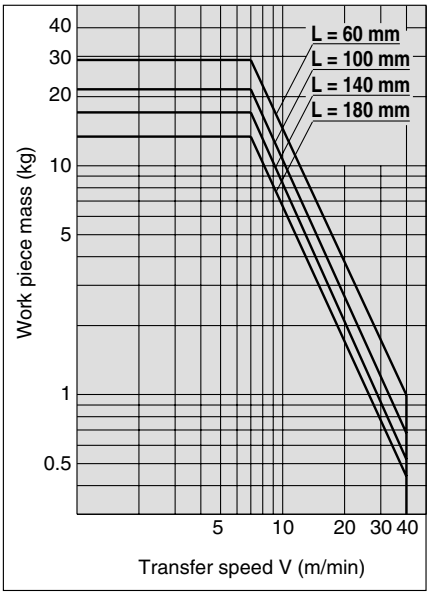
MIW12
MIS12



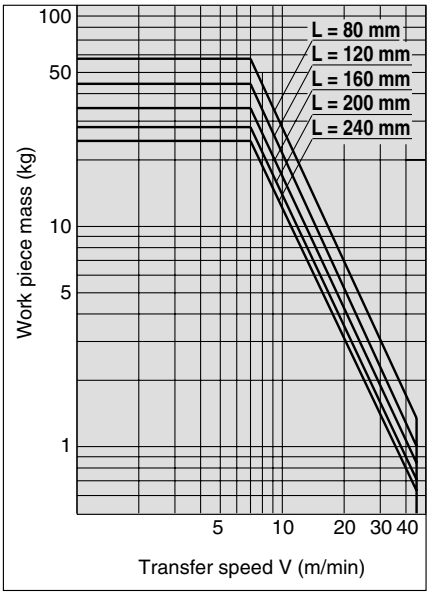
MIW20
MIS20



MIW25
MIS25

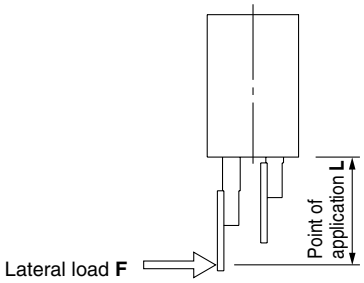


MIW32
MIS32

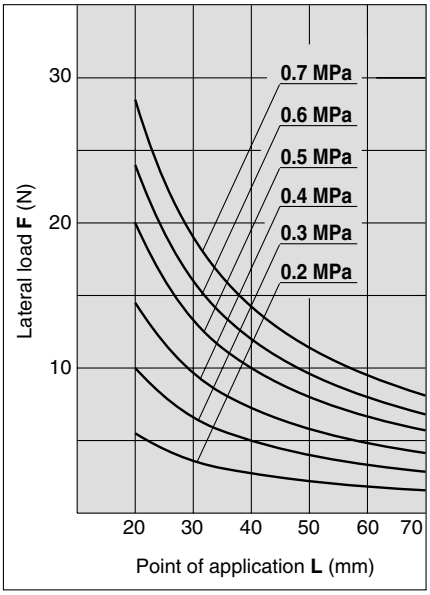


Model Selection

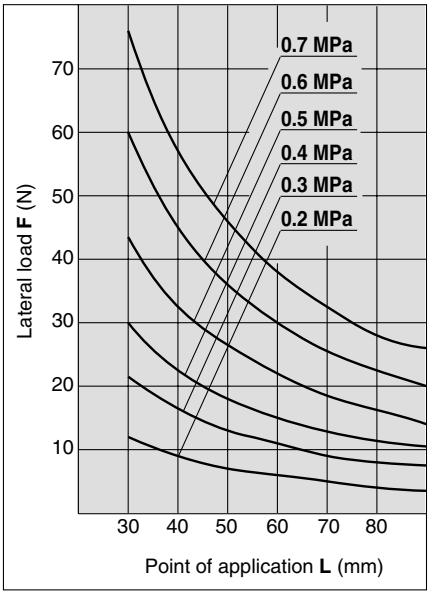
Allowable lateral load



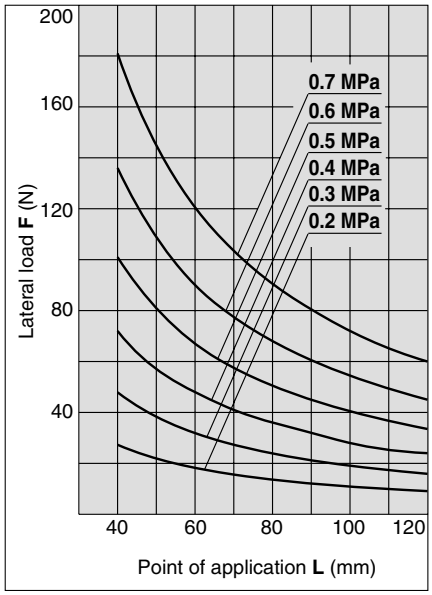
MIW8
MIS8



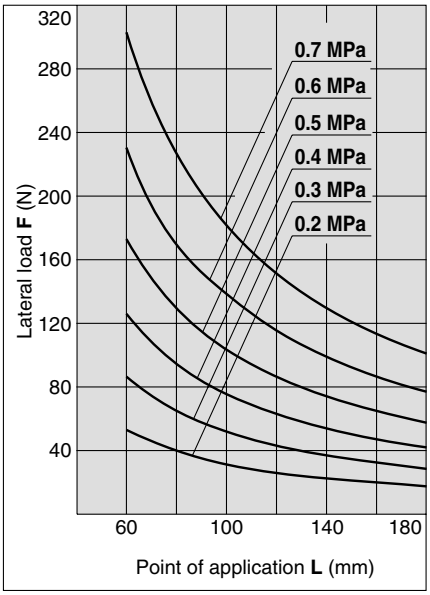
MIW12
MIS12



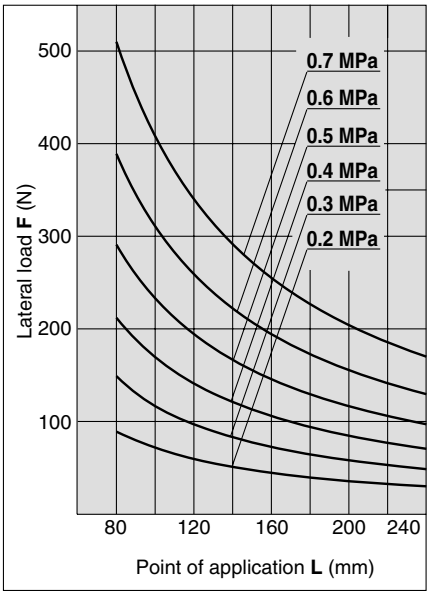
MIW20
MIS20



MIW25
MIS25



MIW32
MIS32



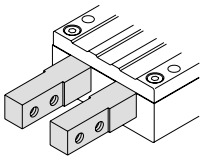
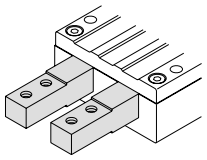
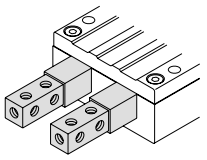
Escapements

Series MIW/MIS

ø8, ø12, ø20, ø25, ø32

How to Order

Finger options

Nil: Basic type (Standard type)	**1**: Tapped on upper and lower faces	**2**: Tapped on all faces (5 surfaces including end surface)
		

Double finger type MIW [12] [ ] - [12] D [1] [A] [S] - [M9BW] [ ] - [ ]

Single finger type MIS [32] [ ] - [50] D [1] [A] [S] - [M9BW] [ ] - [ ]

Cylinder bore

8	8 mm
12	12 mm
20	20 mm
25	25 mm
32	32 mm

Port thread type

Symbol	Type	Bore size
Nil	M thread	ø8, ø12 ø20, ø25
	Rc	ø32
TN	NPT	
TF	G	

Stroke

∗ Refer to the next page for standard stroke table.

Scraper

Nil	No
S	Yes

Stroke adjuster

Nil	No
A	Yes

Type of auto switch

Nil	Without auto switch (built-in magnet)

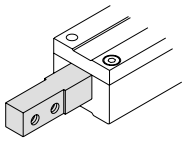
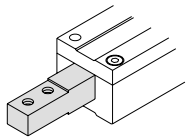
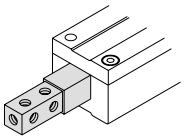
∗ Refer to the table below for auto switch part numbers.

Number of auto switches

Nil	2 pcs.
S	1 pc.

Made to Order
For detailes, refer to page 1423.

Finger options

Nil: Basic type (Standard type)	**1**: Tapped on upper and lower faces	**2**: Tapped on all faces (5 surfaces including end surface)
		

Applicable auto switches/Refer to pages 1719 to 1827 for detailed specifications of auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (output)	Load voltage DC		Load voltage AC	Auto switch models: Perpendicular	Auto switch models: In-line	Lead wire length (m): 0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applicable load	
Solid state switch	—	Grommet	Yes	3-wire (NPN)	24 V	5 V, 12 V	—	**M9NV**	**M9N**	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)				**M9PV**	**M9P**	●	●	●	○	○		
				2-wire		12 V		**M9BV**	**M9B**	●	●	●	○	○	—	
	Diagnostic indication (2-color display)			3-wire (NPN)		5 V, 12 V		**M9NWV**	**M9NW**	●	●	●	○	○	IC circuit	
				3-wire (PNP)				**M9PWV**	**M9PW**	●	●	●	○	○		
				2-wire		12 V		**M9BWV**	**M9BW**	●	●	●	○	○	—	

∗ Lead wire length symbols: 0.5 m ····· Nil (Example) M9NW
1 m ····· M (Example) M9NWM
3 m ····· L (Example) M9NWL
5 m ····· Z (Example) M9NWZ

∗ Solid state auto switches marked with "○" are produced upon receipt of order.

∗ Refer to pages 1784 and 1785 for the details of auto switches with a pre-wired connector.
∗ Auto switches are shipped together (not assembled).

Specifications

Series	**MIW** (Double finger)	**MIS** (Single finger)
Fluid	Air	
Operating pressure	0.2 to 0.7 MPa	
Ambient temperature and fluid temperature	–10 to 60°C (No freezing)	
Lubrication	Non-lube	
Action	Double acting	
Auto switch (optional) Note)	Solid state auto switch (3-wire, 2-wire)	
Stroke tolerance	$^{+1}_{0}$ mm	

Option

Finger options	Standard, Tapped on upper and lower faces, Tapped on all faces (5 surfaces including end surface)
Stroke adjuster (Rear end stroke only)	**MI□8**: Arrangement range 4 mm
	MI□12: Arrangement range 6 mm
	MI□20: Arrangement range 12 mm
	MI□25: Arrangement range 15 mm
	MI□32: Arrangement range 20 mm
Scraper	Can be mounted on standard products

Theoretical Output

Unit: N

Bore size (mm)	Rod size (mm)	Operating direction	Piston area (mm^2)	Operating pressure MPa					
				0.2	0.3	0.4	0.5	0.6	0.7
8	4	OUT	50	10	15	20	26	31	36
		IN	38	7	11	15	19	23	26
12	6	OUT	113	23	34	45	57	68	79
		IN	85	17	26	34	43	51	60
20	10	OUT	314	63	94	126	157	188	220
		IN	236	47	71	94	118	142	165
25	10	OUT	491	98	147	196	245	295	344
		IN	412	82	124	165	206	247	288
32	12	OUT	804	161	241	322	402	482	563
		IN	691	138	207	276	346	415	484

Standard Stroke

Double finger type/MIW

(mm)

Bore size	Stroke
8	8 mm
12	12 mm
20	20 mm
25	25 mm
32	32 mm

∗ For MIW, same stroke as bore size

Single finger type/MIS

(mm)

Bore size	Stroke
8	10, 20 mm
12	10, 20, 30 mm
20	10, 20, 30 mm
25	30, 50 mm
32	30, 50 mm

Made to Order

Made to Order

(For detailes, refer to page 2020.)

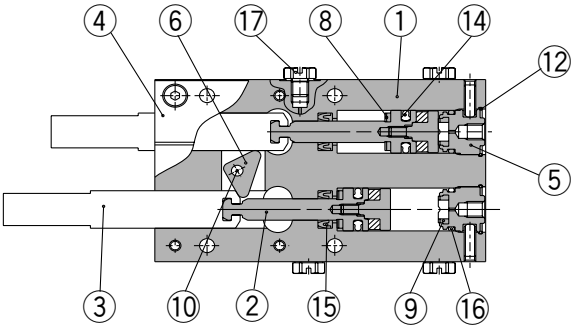
Symbol	Specifications
-X4	Heat resistant (-10 to 100°C)
-X5	Fluororubber seal
-X63	Fluorine grease
-X79	Grease for food

Mass

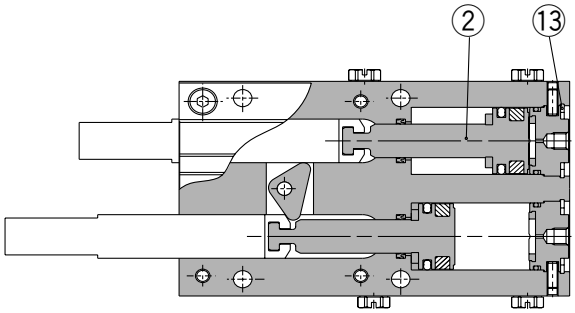
Model	Model	Stroke (mm)	Mass (g)	Increase by stroke adjuster (g)	Increase by scraper (g)
MIW	**MIW8-8D**	8	110	6	3
	MIW12-12D	12	240	10	5
	MIW20-20D	20	650	30	10
	MIW25-25D	25	1550	30	20
	MIW32-32D	32	2650	100	35
MIS	**MIS8-10D**	10	62	3	2
	MIS8-20D	20	80		
	MIS12-10D	10	130	5	3
	MIS12-20D	20	160		
	MIS12-30D	30	190		
	MIS20-10D	10	300	15	5
	MIS20-20D	20	355		
	MIS20-30D	30	410		
	MIS25-30D	30	800	15	10
	MIS25-50D	50	1000		
	MIS32-30D	30	1350	50	18
	MIS32-50D	50	1650		

Construction/Double Finger Type (MIW)

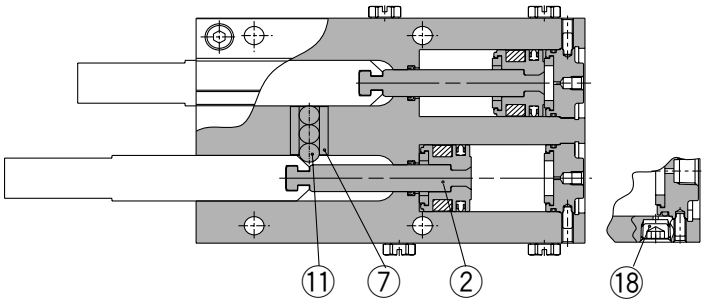
ø8



ø12, ø20

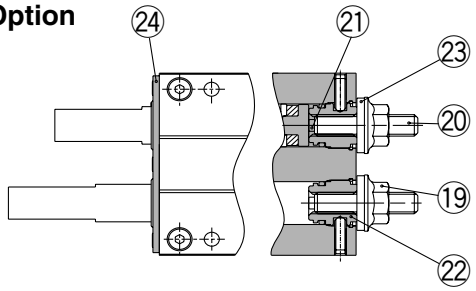


ø25, ø32



(ø32 only)

Option



Scraper **Stroke adjuster**

Component parts

No.	Description	Material	Note
1	**Body**	Aluminium alloy	Hard anodized
2	**Piston assembly**		
3	**Finger**	Carbon steel	Heat treatment/Special treatment
4	**Cover**	Aluminium alloy	Hard anodized
5	**Cap (W)**	Aluminium alloy	White anodized
6	**Cam**	Stainless steel	Heat treatment (MIW8 to 20)
7	**Roller holder**	Stainless steel	Heat treatment (MIW25, 32)
8	**Bumper**	Urethane rubber	
9	**Head bumper**	Urethane rubber	
10	**Needle roller**	High carbon chromium bearing steel	(MIW8 to 20)

No.	Description	Material	Note
11	**Cylinder roller**	Carbon steel	(MIW25, 32)
12	**Clip**	Carbon steel	(MIW8)
13	**R shape retaining ring**	Carbon steel	(MIW12 to 32)
14	**Piston seal**	NBR	
15	**Rod seal**	NBR	
16	**Gasket**	NBR	
17	**Plug**		(MIW8 ··· M-3P)
			(MIW12 to 25 ··· M-5P)
18	**Hexagon socket taper plug**		(MIW32 ··· Rc1/8)

Option: adjuster

No.	Description	Material	Note
19	**Hexagon nut with flange**	Carbon steel	Nickel plated
20	**Adjustment bolt**	Carbon steel	Nickel plated
21	**Adjustment bumper**	Urethane rubber	
22	**Adjustment cap**	Aluminium alloy	White anodized
23	**Die thread**		

Option: scraper

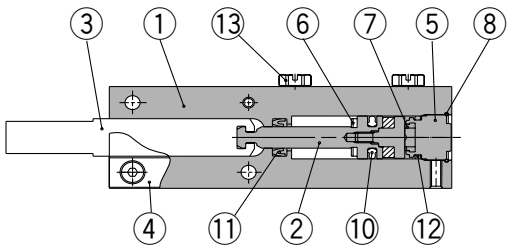
No.	Description	Material	Note
24	**Scraper**	Stainless steel + NBR	

Replacement parts

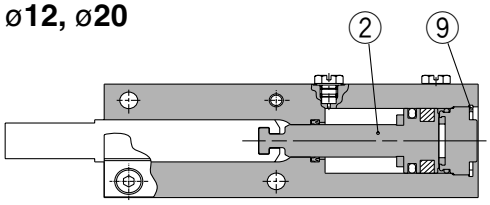
Description / Model	Finger			Seal kit	Scraper assembly	Grease pack
	Standard	Tapped on upper and lower faces	Tapped on all faces			
MIW8-8D	MI-A0801-8	MI-A0802-8	MI-A0803-8	MIW8-PS	MIW-A0804	MH-G01 (contents quantity 30 g)
MIW12-12D	MI-A1201-12	MI-A1202-12	MI-A1203-12	MIW12-PS	MIW-A1204	
MIW20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20	MIW20-PS	MIW-A2004	
MIW25-25D	MI-A2501-25	MI-A2502-25	MI-A2503-25	MIW25-PS	MIW-A2504	
MIW32-32D	MI-A3201-32	MI-A3202-32	MI-A3203-32	MIW32-PS	MIW-A3204	
Main parts No.	③ (1 pc.)			⑭, ⑮, ⑯	㉔	

Construction/Single Finger Type (MIS)

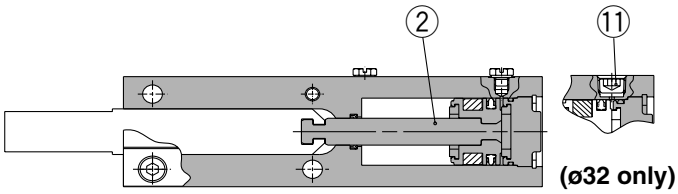
ø8



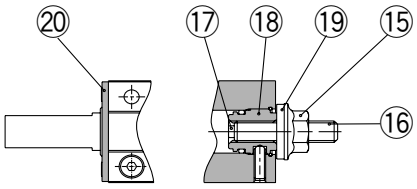
ø12, ø20



ø25, ø32



Option



Scraper **Stroke adjuster**

Component parts

No.	Description	Material	Note
1	**Body**	Aluminium alloy	Hard anodized
2	**Piston assembly**		
3	**Finger**	Carbon steel	Heat treatment/Special treatment
4	**Cover**	Aluminium alloy	Hard anodized
5	**Cap (S)**	Aluminium alloy	White anodized
6	**Bumper**	Urethane rubber	
7	**Head bumper**	Urethane rubber	
8	**Clip**	Carbon steel	(MIS8)
9	**R shape retaining ring**	Carbon steel	(MIS12 to 32)

No.	Description	Material	Note
10	**Piston seal**	NBR	
11	**Rod seal**	NBR	
12	**Gasket**	NBR	
13	**Plug**		(MIS8 ··· M-3P)
			(MIS12 to 25 ··· M-5P)
14	**Hexagon socket taper plug**		(MIS32 ··· Rc1/8)

Option: adjuster

No.	Description	Material	Note
15	**Hexagon nut with flange**	Carbon steel	Nickel plated
16	**Adjustment bolt**	Carbon steel	Nickel plated
17	**Adjustment bumper**	Urethane rubber	
18	**Adjustment cap**	Aluminium alloy	White anodized
19	**Die thread**		

Option: scraper

No.	Description	Material	Note
20	**Scraper**	Stainless steel + NBR	

Replacement parts

Description / Model	Finger			Seal kit	Scraper assembly	Grease pack
	Standard	Tapped on upper and lower faces	Tapped on all faces			
MIS8-10D	MI-A0801-10	MI-A0802-10	MI-A0803-10	MIS8-PS	MIS-A0804	MH-G01 (contents quantity 30 g)
MIS8-20D	MI-A0801-20	MI-A0802-20	MI-A0803-20			
MIS12-10D	MI-A1201-10	MI-A1202-10	MI-A1203-10	MIS12-PS	MIS-A1204	
MIS12-20D	MI-A1201-20	MI-A1202-20	MI-A1203-20			
MIS12-30D	MI-A1201-30	MI-A1202-30	MI-A1203-30			
MIS20-10D	MI-A2001-10	MI-A2002-10	MI-A2003-10	MIS20-PS	MIS-A2004	
MIS20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20			
MIS20-30D	MI-A2001-30	MI-A2002-30	MI-A2003-30			
MIS25-30D	MI-A2501-30	MI-A2502-30	MI-A2503-30	MIS25-PS	MIS-A2504	
MIS25-50D	MI-A2501-50	MI-A2502-50	MI-A2503-50			
MIS32-30D	MI-A3201-30	MI-A3202-30	MI-A3203-30	MIS32-PS	MIS-A3204	
MIS32-50D	MI-A3201-50	MI-A3202-50	MI-A3203-50			
Main parts No.	③ (1 pc.)			⑩, ⑪, ⑫	⑳	

Dimensions/Double Finger Type

MIW□-□D

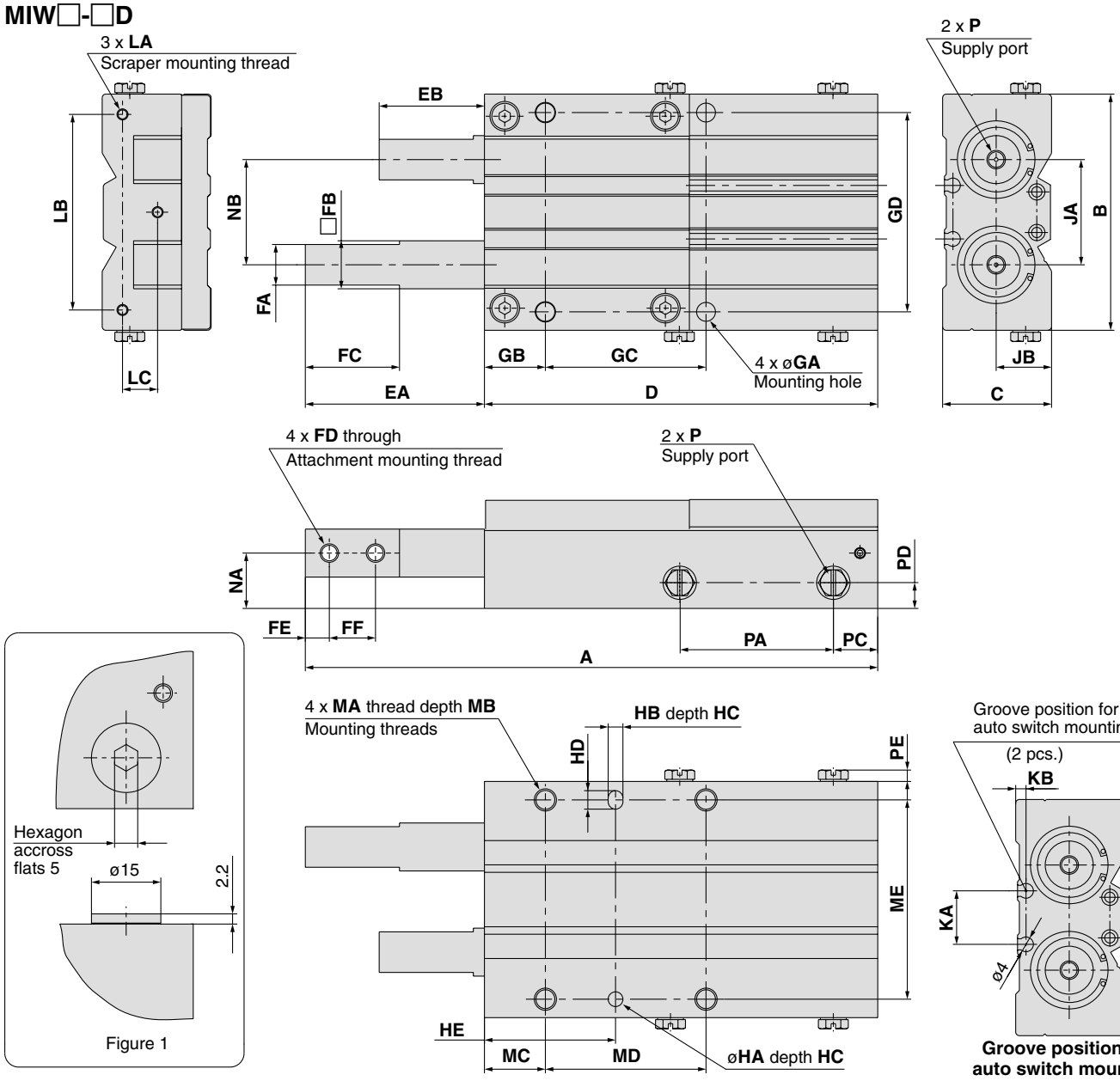


Figure 1

Groove position for auto switch mounting

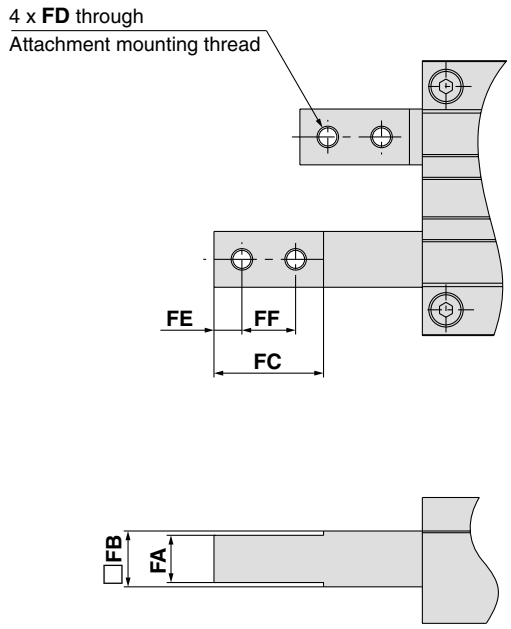
Supply ports are provided on both sides, and on cap side.
Ports on both sides are sealed with plug at the time of shipment.
ø8 : Plug part no. M-3P (Width across flats 5)
ø12 to ø25: Plug part no. M-5P (Width across flats 7)
ø32 : Hexagon socket head taper plug (Width across flats 5)
∗ Refer to the Figure 1 for G thread

(mm)

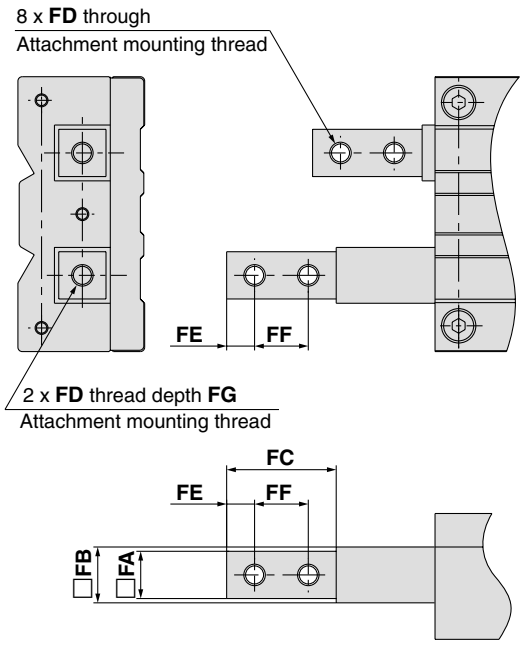
Model	A	B	C	D	EA	EB	FA	FB	FC	FD	FE	FF	FG	GA	GB	GC	GD
MIW8-8	83	34	16	57	26	18	$6^{0}_{-0.1}$	$7h9^{0}_{-0.036}$	15	M3 x 0.5	4	7	6 (Effective depth 2.5)	2.6	9	22	28
MIW12-12	111	44	21	76	35	23	$8^{0}_{-0.1}$	$10h9^{0}_{-0.036}$	19	M3 x 0.5	4.5	9.5	6 (Effective depth 3)	3.3	12.5	34	37
MIW20-20	155	64	29.5	106.5	48.5	28.5	$11^{0}_{-0.1}$	$13h9^{0}_{-0.043}$	25.5	M5 x 0.8	6.5	12.5	10 (Effective depth 4)	5.1	16.5	43.5	54
MIW25-25	200	84	40	134	66	41	$15^{0}_{-0.1}$	$17h9^{0}_{-0.043}$	37	M6 x 1	10	17	15 (Effective depth 7)	6.8	20	58	71
MIW32-32	256	95	47	169	87	55	$19.5^{0}_{-0.1}$	$21h9^{0}_{-0.052}$	51	M8 x 1.25	12.5	22	17 (Effective depth 8.5)	8.6	24.5	73	80

Model	HA, HB	HC	HD	HE	JA	JB	KA	KB	LA	LB
MIW8-8	$2H9^{+0.025}_{0}$	2	3	15	14.5	7.5	20.3	1.6	M2 x 0.4	28.4
MIW12-12	$2.5H9^{+0.025}_{0}$	4	3.5	25	19	11	7.6	2.2	M2.6 x 0.45	37
MIW20-20	$4H9^{+0.030}_{0}$	5	5	35.5	28.5	15	14.5	2.8	M3 x 0.5	53
MIW25-25	$5H9^{+0.030}_{0}$	5	7	40	35.5	20	24.5	3	M3 x 0.5	70
MIW32-32	$6H9^{+0.030}_{0}$	6	8	50	44.5	25	24.1	2.5	M4 x 0.7	81

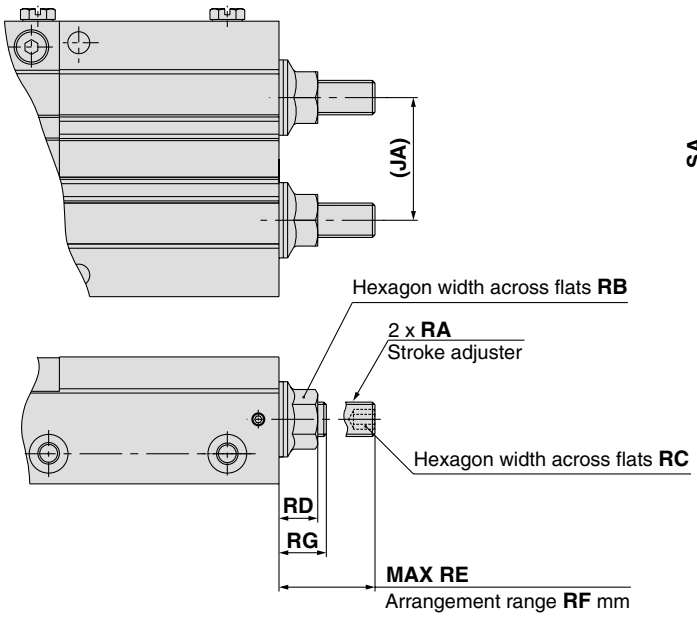
Finger options
Tapped on upper and lower faces



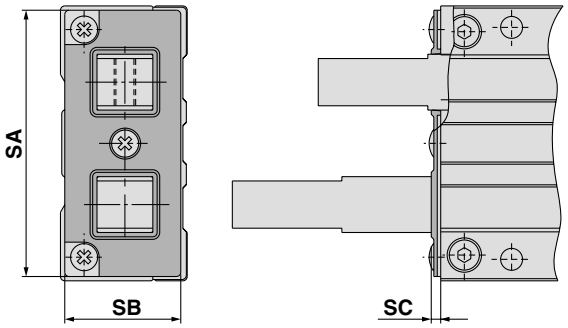
Tapped on all faces



Stroke adjuster



Scraper



Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

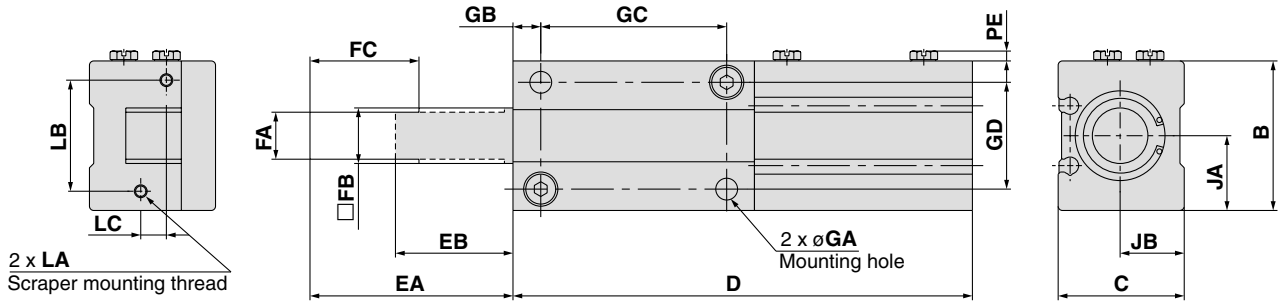
(mm)

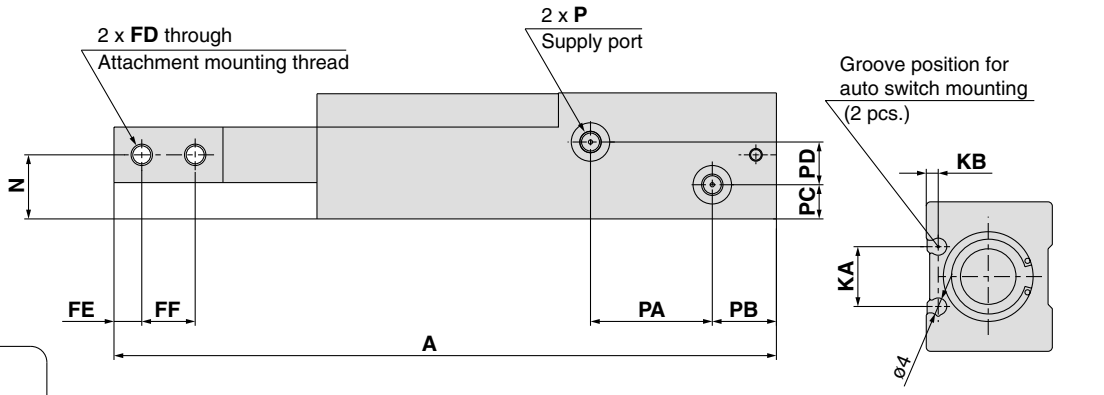
Model	LC	MA	MB	MC	MD	ME	NA	NB	P	PA	PB	PC	PD	PE	RA	RB	RC	RD
MIW8-8	4.5	M3 x 0.5	6	9	22	28	7.5	14.5	M3 x 0.5	22.5	24	8	4.5	2.2	M4 x 0.7	7	2	5.7
MIW12-12	7.5	M4 x 0.7	7	12.5	34	37	11	19	M5 x 0.8	25	27	10	6	2.8	M5 x 0.8	8	2.5	6
MIW20-20	9.5	M6 x 1	10	16.5	43.5	54	15	28.5	M5 x 0.8	41.5	44	12	7	2.7	M8 x 1	12	4	9
MIW25-25	12	M8 x 1.25	12	20	58	71	20	35.5	M5 x 0.8	50	55	14	8.5	2.7	M8 x 1	12	4	9
MIW32-32	16.5	M10 x 1.5	15	24.5	73	80	25	44.5	Rc1/8	69.5	75.5	14.5	11	—	M12 x 1.25	17	6	12.4

Model	RE	RF	RG	SA	SB	SC
MIW8-8	12.5	4	8.5	33	14.5	1.4
MIW12-12	14	6	8	43	18.5	1.8
MIW20-20	22.5	12	10.5	62	27	2.2
MIW25-25	26	15	11	81	35	2.8
MIW32-32	33	20	13	93	42	3.4

Dimensions/Single Finger Type

MIS□-□D





Groove position for auto switch mounting

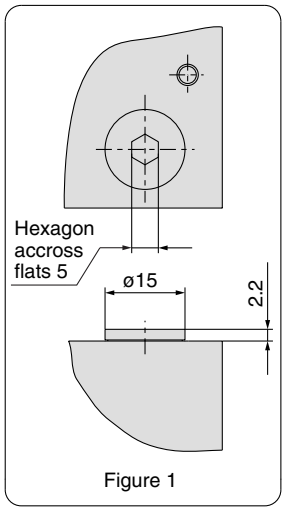
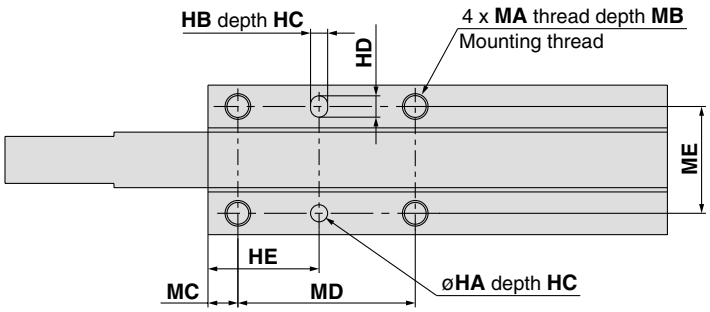
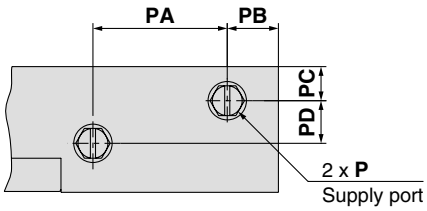


Figure 1





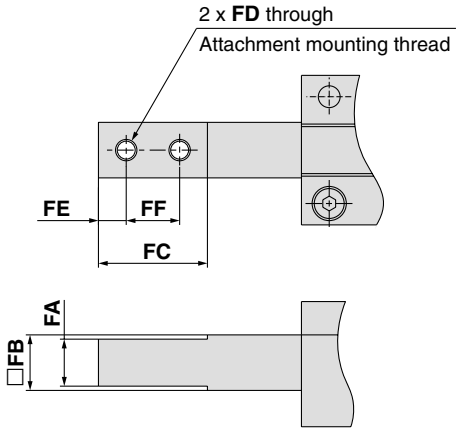
Supply ports are provided on both sides.
A port on a side is sealed with plug at the time of shipment.
- ø8 : Plug part no. M-3P (Width across flats 5)
- ø12 to ø25: Plug part no. M-5P (Width across flats 7)
- ø32 : Hexagon socket head taper plug (Width across flats 5)

∗ Refer to the Figure 1 for G thread

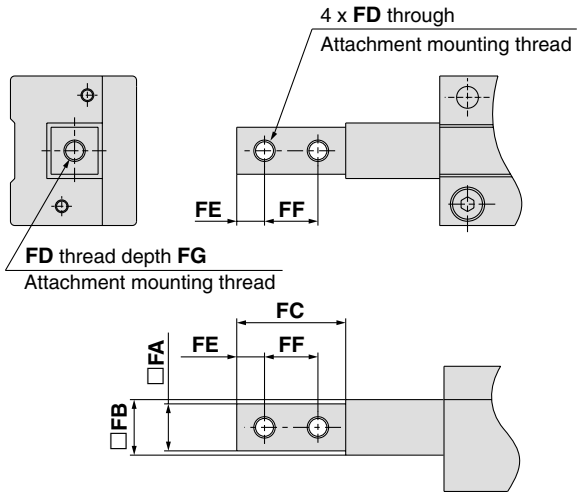
Model	A	B	C	D	EA	EB	FA	FB	FC	FD	FE	FF	FG	GA	GB	GC	GD	HA, HB
MIS8-10	87	19	16	59	28	18	$6^{0}_{-0.1}$	7h9 $^{0}_{-0.036}$	15	M3 x 0.5	4	7	6 (Effective depth 2.5)	2.6	4	20	13	2H9 $^{+0.025}_{0}$
MIS8-20	117			79	38											30		
MIS12-10	105	26	21	72	33	23	$8^{0}_{-0.1}$	10h9 $^{0}_{-0.036}$	19	M3 x 0.5	4.5	9.5	6 (Effective depth 3)	3.3	5	28	18	2.5H9 $^{+0.025}_{0}$
MIS12-20	135			92	43											38		
MIS12-30	165			112	53											48		
MIS20-10	125	35	29.5	86.5	38.5	28.5	$11^{0}_{-0.1}$	13h9 $^{0}_{-0.043}$	25.5	M5 x 0.8	6.5	12.5	10 (Effective depth 4)	5.1	7	32	25	4H9 $^{+0.030}_{0}$
MIS20-20	155			106.5	48.5											42		
MIS20-30	185			126.5	58.5											52		
MIS25-30	215	41	40	144	71	41	$15^{0}_{-0.1}$	17h9 $^{0}_{-0.043}$	37	M6 x 1	10	17	15 (Effective depth 7)	6.8	10	55	28	5H9 $^{+0.030}_{0}$
MIS25-50	270			184	91											75		
MIS32-30	250	50	47	165	85	55	$19.5^{0}_{-0.1}$	21h9 $^{0}_{-0.052}$	51	M8 x 1.25	12.5	22	17 (Effective depth 8.5)	8.6	12	64	34	6H9 $^{+0.030}_{0}$
MIS32-50	310			205	105											84		

Finger options

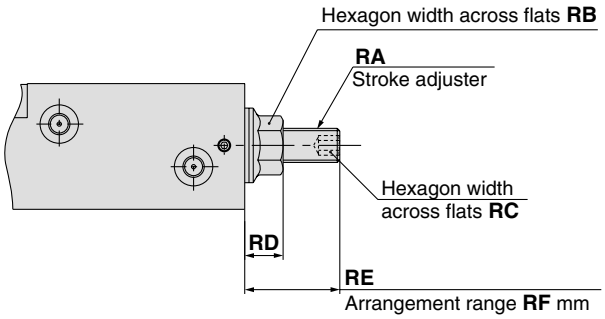
Tapped on upper and lower faces



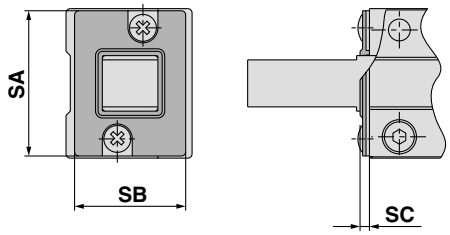
Tapped on all faces



With adjuster



With scraper



Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

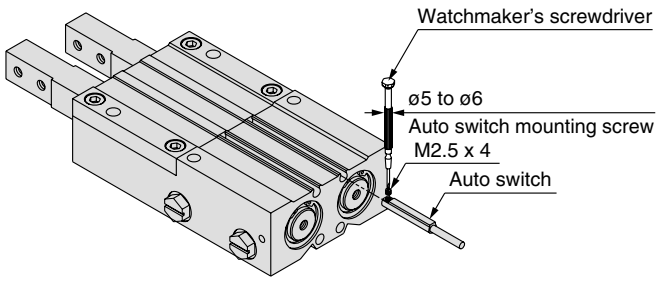
Model	HC	HD	HE	JA	JB	KA	KB	LA	LB	LC	MA	MB	MC	MD	ME	N	P	PA	PB	PC
MIS8-10	2	3	14	9.5	7.5	6.2	1.6	M2 x 0.4	14	3	M3 x 0.5	5	4	20	13	7.5	M3 x 0.5	19	8	4.5
MIS8-20														30				29		
MIS12-10	4	3.5	17.5	13	11	11.6	2.2	M2.6 x 0.45	19	4	M4 x 0.7	7	5	28	18	11	M5 x 0.8	19	10	6
MIS12-20														38				29		
MIS12-30														48				39		
MIS20-10	5	5	26	17.5	15	14	2.8	M3 x 0.5	26	6	M6 x 1	10	7	32	25	15	M5 x 0.8	20.5	12	8
MIS20-20														42				30.5		
MIS20-30														52				40.5		
MIS25-30	5	7	32	20.5	20	11	3	M3 x 0.5	32	10	M8 x 1.25	14	10	55	28	20	M5 x 0.8	47	14	12
MIS25-50														75				67		
MIS32-30	6	8	40	25	25	20.4	2.5	M4 x 0.7	39	12	M10 x 1.5	15	12	64	34	25	Rc1/8	47	14.5	11
MIS32-50														84				67		

Model	PD	PE	RA	RB	RC	RD	RE	RF	RG	SA	SB	SC
MIS8-10	6	2.2	M4 x 0.7	7	2	5.7	12.5	4	8.5	18.6	14	1.4
MIS8-20												
MIS12-10	7	2.8	M5 x 0.8	8	2.5	6	14	6	8	24	18	1.8
MIS12-20												
MIS12-30												
MIS20-10	10	2.7	M8 x 1	12	4	9	22.5	12	10.5	34	26	2.2
MIS20-20												
MIS20-30												
MIS25-30	14	2.7	M8 x 1	12	4	9	26	15	11	40	36	2.8
MIS25-50												
MIS32-30	27	—	M12 x 1.25	17	6	12.4	33	20	13	49	41	3.4
MIS32-50												

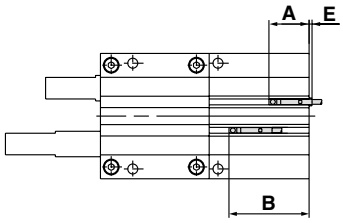
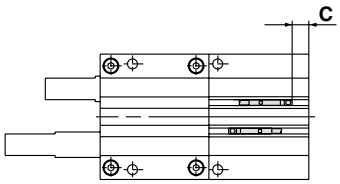
Auto Switch Mounting

When mounting an auto switch, insert the auto switch in the switch mounting groove on the escapement from the direction as below figure. Having set the mounting position, tighten the attached auto switch mounting screws with a flat head watchmaker's screwdriver.

* When adjusting the auto switch mounting screws, use a watchmaker's screwdriver with a handle 5 to 6 mm in diamterer. (This is to prevent fracture due to an excessive torque.) The guideline of the tightening torque is 0.1 to 0.15 N·m.



Proper mounting position for stroke end detection

Model	Electrical entry is in the → direction	Electrical entry is in the ← direction
M9□ M9□V M9□W (V)		

Auto Switch Operating Range

MIW (mm)

Auto switch model	ø8	ø12	ø20	ø25	ø32
D-M9□(V) D-M9□W(V)	3	2.5	4	5.5	7

MIS (mm)

Auto switch model	ø8	ø12	ø20	ø25	ø32
D-M9□(V) D-M9□W(V)	3	3.5	4.5	5.5	7

Note) The operating ranges are provided as guidelines including hysteresis and are not guaranteed values (with ±30% variations). Hysteresis may fluctuate due to the operating environments.

(mm)

Model		Proper mounting position D-M9□ D-M9□W	Proper mounting position D-M9□V D-M9□WV
MIW8-8D	A	16.5	
	B	25	
	C	4.5	
	D	—	
	E	6	4
MIS8-10D	A	16.5	
	B	27	
	C	4.5	
	D	—	
	E	6	4
MIS8-20D	A	16.5	
	B	37	
	C	4.5	
	D	—	
	E	6	4
MIW12-12D	A	18.5	
	B	31	
	C	6.5	
	D	—	
	E	3.5	1.5
MIS12-10D	A	18.5	
	B	29	
	C	6.5	
	D	—	
	E	3.5	1.5
MIS12-20D	A	18.5	
	B	39	
	C	6.5	
	D	—	
	E	3.5	1.5
MIS12-30D	A	18.5	
	B	49	
	C	6.5	
	D	—	
	E	3.5	1.5
MIW20-20D	A	20.5	
	B	41	
	C	8.5	
	D	—	
	E	4	2
MIS20-10D	A	20.5	
	B	31	
	C	8.5	
	D	—	
	E	4	2
MIS20-20D	A	20.5	
	B	51	
	C	8.5	
	D	—	
	E	4	2
MIS20-30D	A	20.5	
	B	61	
	C	8.5	
	D	—	
	E	4	2
MIW25-25D	A	7.5	
	B	33	
	C	21	
	D	—	
	E	—	—
MIS25-30D	A	7.5	
	B	38	
	C	21	
	D	—	
	E	—	—
MIS25-50D	A	7.5	
	B	38	
	C	21	
	D	—	
	E	—	—
MIW32-32D	A	8.5	
	B	41	
	C	29	
	D	—	
	E	—	—
MIS32-30D	A	8.5	
	B	39	
	C	29	
	D	—	
	E	—	—
MIS32-50D	A	8.5	
	B	59	
	C	29	
	D	—	
	E	—	—

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Specific Product Precautions 1

Be sure to read before handling.
Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Selection

⚠ Warning

1. Design the attachment to be light and short.

1) A long and heavy attachment can cause a large inertia force in operation, sometimes affecting the life time.
2) Design the attachment to be as short and light as possible even within the limitation.

Mounting

⚠ Warning

1. Do not scratch or gouge the escapement by dropping or bumping it when mounting.

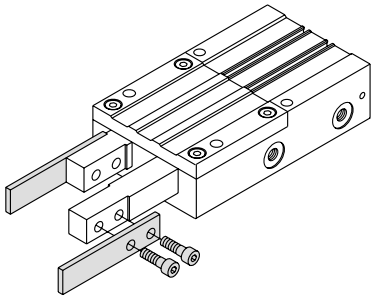
Even a slight deformation can cause inaccuracy or malfunction.

2. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque beyond the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

Mounting attachment on finger

When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.
Mount attachments by inserting bolts, etc. into the female mounting threads on the fingers and tightening with the torque shown in the table below.



Model	Bolt	Max tightening torque (N·m)
MIW8	M3 x 0.5	0.88
MIS8		
MIW12	M3 x 0.5	0.88
MIS12		
MIW20	M5 x 0.8	4.3
MIS20		
MIW25	M6 x 1	7.3
MIS25		
MIW32	M8 x 1.25	17.5
MIS32		

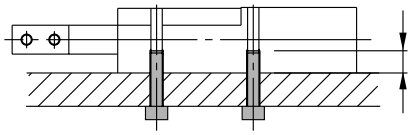
3. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque above the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

Mounting

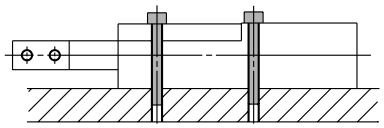
Mounting

Body tap



Model	Bolt	Max tightening torque (N·m)	Max screw-in depth (mm)
MIW8	M3 x 0.5	0.88	6
MIS8		0.63	4.5
MIW12	M4 x 0.7	1.5	6
MIS12			
MIW20	M6 x 1	5.2	9
MIS20			
MIW25	M8 x 1.25	12.5	12
MIS25			
MIW32	M10 x 1.5	24.5	15
MIS32			

Body through hole



Model	Bolt	Max tightening torque (N·m)
MIW8	M2.5 x 0.45	0.5
MIS8		
MIW12	M3 x 0.5	0.88
MIS12		
MIW20	M5 x 0.8	4.3
MIS20		
MIW25	M6 x 1	7.3
MIS25		
MIW32	M8 x 1.25	17.5
MIS32		

⚠ Caution

1. When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.

Otherwise malfunction may result.

2. Please do not scratch or gouge the sliding part of the finger.

It may increase the sliding resistance or cause abrasion.

3. Use a speed controller, etc. to keep the operating speed of the finger within the proper range.

Otherwise the life time may be adversely affected by inertia force of the attachment.

4. Conduct meter-out control to throttle down the speed.

Applicable speed controller
Direct connection type –AS120□ Piping type – AS1001F
Direct connection type –AS220□ Piping type – AS2001F etc.

Series MIW/MIS
Specific Product Precautions 2

Be sure to read before handling.
Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Changing of Piping Directions

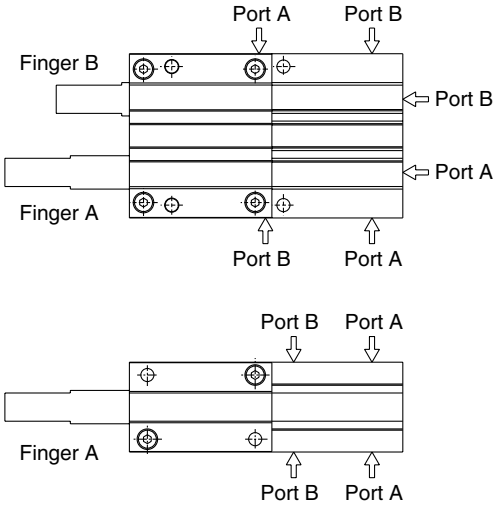
⚠ Caution

1. Please observe the specified torque limits when tightening a plug to change the piping directions.

A tightening torque above the specified limits can cause a damage to the plug, while tightening torque below the specified limits can cause a damage to seal or the screw come loose during the operation.

Model	Port size	How to tight
MIW8 **MIS8**	M3 x 0.5 (Plug part no: M-3P)	Turn another 1/4 turn with a tool after manual tightening.
MIW12 **MIS12**	M5 x 0.8 (Plug part no: M-5P)	Turn another 1/6 turn with a tool after manual tightening.
MIW20 **MIS20**		
MIW25 **MIS25**		
MIW32 **MIS32**	Rc1/8	Tightening torque 7 to 9 N·m

Supply port operation



Pressured from A port → Finger A extends, finger B retracts
Pressure from B port → Finger B extends, finger A retracts

Handling of Adjuster Options

Stroke adjuster

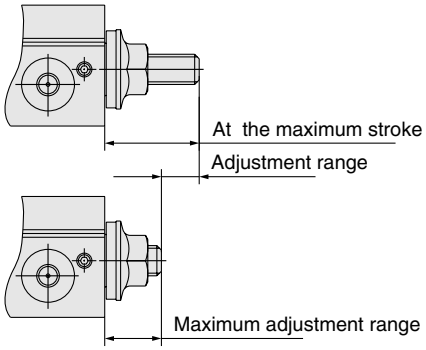
⚠ Warning

1. Observe the specified adjustment range as shown on right when adjusting with a stroke adjuster.

Bolts may shoot out when adjusting stroke adjuster over the maximum stroke as shown on right. Be sure to observe the specified adjustment range, otherwise malfunction may results.

Handling of Adjuster Options

Model	At the maximum stroke (mm)	At the maximum adjustment (mm)	Adjustment range (mm)
MIW8	12.5	8.4	4
MIS8			
MIW12	14	8	6
MIS12			
MIW20	22.5	10.5	12
MIS20			
MIW25	26	11	15
MIS25			
MIW32	33	13	20
MIS32			



2. Be sure to use specified adjuster bolts for replacement.

Otherwise, fracture may be caused by an impact etc.

3. Refer to the table below for the lock nut tightening torque.

Insufficient tightening can cause air leakage.

Model	Tightening torque (N·m)
MIW8	1.2 to 1.5
MIS8	
MIW12	2.5 to 3.0
MIS12	
MIW20	10.5 to 12.5
MIS20	
MIW25	10.5 to 12.5
MIS25	
MIW32	34 to 42
MIS32	

Operating Environment

⚠ Caution

1. Do not use in an environment where the product is directly exposed to liquid such as cutting lubricant.

Avoid use in an environment where the product is exposed to cutting lubricant, liquid coolant or oil mist. It can cause rattles, increase in sliding resistance and air leakage.

2. Do not use in an environment where the product is directly exposed to foreign matter such as dust, coarse particular, chips and polishing powder from a spatter grinder, etc.

It can cause rattles, increase in sliding resistance and air leakage.

Specific Product Precautions 3

Be sure to read before handling.
Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Operating Environment

⚠ Caution

3. Provide shading in an environment where the product is exposed to the sunlight.

4. Block off heat radiation in an environment where a heat source is at a close distance.

Block off heat radiation with a cover if a heat source is at a close distance because the temperature of the product can rise to exceed the operating temperature range due to radiation.

5. Do not use in an environment where vibration or impact occurs.

Contact SMC about use under such conditions because it can cause fracture or malfunction.

Lubrication

⚠ Caution

1. The non-lubricant type escapement is lubricated at the factory and does not need further lubrication for use.

In case the product is lubricated by the customer, apply class 1 turbin oil (non additive) ISO VG32.
In case the product is lubricated by the customer, be sure to continue lubrication.
If it is discontinued, malfunction may result due to loss of initial lubricant.

Maintenance

⚠ Warning

1. Keep away hands and other body parts from the fingers of the escapement or movement range of the attachment.

It can lead to an injury or accident.

2. When removing the escapement, first block off or remove the work piece on the primary side of the escapement, release compressed air and remove it.

If the work piece remains, it can be transferred by mistake and cause failure to the equipment on the secondary side.

Finger replacement

1. Remove the hexagon socket head screws.

2. Remove the cover.

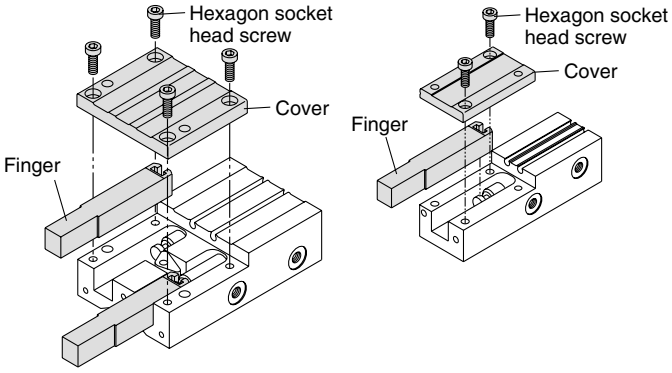
3. Replace the finger.

- Apply the specified grease to the sliding part and T groove part of the finger.
- Insert the piston in the T groove so that it will be hooked there.

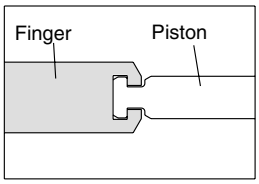
4. Mount the cover and tighten the hexagon socket head screws with the tightening torque in the table below.

Bore size	Hexagon socket head screw	Hexagon width across flats	Tightening torque (N·m)
8	M2 x 6	1.5	0.24
12	M2.5 x 6	2	0.36
20	M4 x 10	3	1.5
25	M5 x 14	4	3.0
32	M6 x 15	5	5.2

Maintenance



Finger and position connection



For information on the replacement parts and specified grease, refer to the replacement parts on page 1425.

Scraper Option

⚠ Caution

1. Please observe the specified torque limits when mounting a scraper.

A tightening torque above the specified limits can cause a damage, while tightening torque below the specified limits can cause a dislocation or drop off.

Tightening torque

Model	Bolt (N·m)
MIW8	0.176
MIS8	
MIW12	0.36
MIS12	
MIW20	0.63
MIS20	
MIW25	0.63
MIS25	
MIW32	1.5
MIS32